

# LINEAR EQUATIONS WITH UNKNOWNS FROM A MULTIPLICATIVE GROUP WHOSE SOLUTIONS LIE IN A SMALL NUMBER OF SUBSPACES

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**ABSTRACT.** Let  $K$  be a field of characteristic 0 and let  $(K^*)^n$  denote the  $n$ -fold cartesian product of  $K^*$ , endowed with coordinatewise multiplication. Let  $\Gamma$  be a subgroup of  $(K^*)^n$  of finite rank. We consider equations  $(*)$   $a_1x_1 + \cdots + a_nx_n = 1$  in  $\mathbf{x} = (x_1, \dots, x_n) \in \Gamma$ , where  $\mathbf{a} = (a_1, \dots, a_n) \in (K^*)^n$ . Two tuples  $\mathbf{a}, \mathbf{b} \in (K^*)^n$  are called  $\Gamma$ -equivalent if there is a  $\mathbf{u} \in \Gamma$  such that  $\mathbf{b} = \mathbf{u} \cdot \mathbf{a}$ . Győry and the author [4] showed that for all but finitely many  $\Gamma$ -equivalence classes of tuples  $\mathbf{a} \in (K^*)^n$ , the set of solutions of  $(*)$  is contained in the union of not more than  $2^{(n+1)!}$  proper linear subspaces of  $K^n$ . Later, this was improved by the author [3] to  $(n!)^{2n+2}$ . In the present paper we will show that for all but finitely many  $\Gamma$ -equivalence classes of tuples of coefficients, the set of non-degenerate solutions of  $(*)$  (i.e., with non-vanishing subsums) is contained in the union of not more than  $2^n$  proper linear subspaces of  $K^n$ . Further we give an example showing that  $2^n$  cannot be replaced by a quantity smaller than  $n$ .

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## 1. INTRODUCTION

Let  $K$  be a field of characteristic 0. Denote by  $(K^*)^n$  the  $n$ -fold direct product of the multiplicative group  $K^*$ . The group operation of  $(K^*)^n$  is coordinatewise multiplication, i.e., if  $\mathbf{x} = (x_1, \dots, x_n)$ ,  $\mathbf{y} = (y_1, \dots, y_n) \in (K^*)^n$ , then  $\mathbf{x} \cdot \mathbf{y} = (x_1y_1, \dots, x_ny_n)$ . A subgroup  $\Gamma$  of  $(K^*)^n$  is said to be of finite rank if there are  $\mathbf{u}_1, \dots, \mathbf{u}_r \in \Gamma$  with the property that for every  $\mathbf{x} \in \Gamma$  there are  $z \in \mathbb{Z}_{>0}$  and  $z_1, \dots, z_r \in \mathbb{Z}$  such that  $\mathbf{x}^z = \mathbf{u}_1^{z_1} \cdots \mathbf{u}_r^{z_r}$ . The smallest  $r$  for which such  $\mathbf{u}_1, \dots, \mathbf{u}_r$

exist is called the rank of  $\Gamma$ ; the rank of  $\Gamma$  is equal to 0 if all elements of  $\Gamma$  have finite order.

For the moment, let  $n = 2$ . We consider the equation

$$(1.1) \quad a_1x_1 + a_2x_2 = 1 \quad \text{in } \mathbf{x} = (x_1, x_2) \in \Gamma,$$

where  $\mathbf{a} = (a_1, a_2) \in (K^*)^2$  and where  $\Gamma$  is a subgroup of  $(K^*)^2$  of finite rank  $r$ . In 1996, Beukers and Schlickewei [2] showed that (1.1) has at most  $2^{8(r+2)}$  solutions.

Two pairs  $\mathbf{a} = (a_1, a_2), \mathbf{b} = (b_1, b_2)$  are called  $\Gamma$ -equivalent if there is an  $\mathbf{u} \in \Gamma$  such that  $\mathbf{b} = \mathbf{u} \cdot \mathbf{a}$ . Clearly, two equations (1.1) with  $\Gamma$ -equivalent pairs of coefficients  $\mathbf{a}$  have the same number of solutions. In 1988, Győry, Stewart, Tijdeman and the author [5] showed that there is a finite number of  $\Gamma$ -equivalence classes, such that for all tuples  $\mathbf{a} = (a_1, a_2)$  outside the union of these classes, equation (1.1) has at most *two* solutions. (In fact they considered only groups  $\Gamma = U_S \times U_S$  where  $U_S$  is the group of  $S$ -units in a number field, but their argument works in precisely the same way for the general case.) The upper bound 2 is best possible. We mention that this result is ineffective in that the method of proof does not allow to determine the exceptional equivalence classes. Bérczes [1, Lemma 3] calculated the upper bound  $2e^{30^{20}(r+2)}$  for the number of exceptional equivalence classes.

Now let  $n \geq 3$ . We deal with equations

$$(1.2) \quad a_1x_1 + \cdots + a_nx_n = 1 \quad \text{in } \mathbf{x} = (x_1, \dots, x_n) \in \Gamma,$$

where  $\mathbf{a} = (a_1, \dots, a_n) \in (K^*)^n$  and where  $\Gamma$  is a subgroup of  $(K^*)^n$  of finite rank  $r$ . A solution  $\mathbf{x}$  of (1.2) is called non-degenerate if

$$(1.3) \quad \sum_{i \in I} a_i x_i \neq 0 \quad \text{for each non-empty subset } I \text{ of } \{1, \dots, r\}.$$

It is easy to show that there are groups  $\Gamma$  such that any degenerate solution of (1.2) gives rise to an infinite set of solutions. Schlickewei, Schmidt and the author [6] showed that equation (1.2) has at most  $e^{(6n)^{3n}(r+1)}$  non-degenerate solutions. Their proof was based on a version of the quantitative Subspace Theorem, i.e., on the Thue-Siegel-Roth-Schmidt method. Recently, by a very different approach based on a method of Vojta and Faltings, Rémond [8] proved a general quantitative result for subvarieties of tori, which includes as a special case that for  $n \geq 3$  equation (1.2) has at most  $2^{n^{4n^2}(r+1)}$  non-degenerate solutions.

Two tuples  $\mathbf{a}, \mathbf{b} \in (K^*)^n$  are called  $\Gamma$ -equivalent if  $\mathbf{b} = \mathbf{u} \cdot \mathbf{a}$  for some  $\mathbf{u} \in \Gamma$ . Győry, Stewart, Tijdeman and the author [5] showed that for every sufficiently large  $r$ , there are a subgroup  $\Gamma$  of  $(\mathbb{Q}^*)^n$  of rank  $r$ , and infinitely many  $\Gamma$ -equivalence classes of tuples  $\mathbf{a} = (a_1, \dots, a_n) \in (\mathbb{Q}^*)^n$ , such that equation (1.2) has at least  $e^{2r^{1/2}(\log r)^{-1/2}}$  non-degenerate solutions. This shows that in contrast to the case  $n = 2$ , for  $n \geq 3$  there is no uniform bound  $C$  independent of  $\Gamma$  such that for all tuples  $\mathbf{a}$  outside finitely many  $\Gamma$ -equivalence classes the number of non-degenerate solutions of (1.2) is at most  $C$ .

It turned out to be more natural to consider the minimal number  $m$  such that the set of solutions of (1.2) can be contained in the union of  $m$  proper linear subspaces of  $K^n$ . Notice that this minimal number  $m$  does not change if  $\mathbf{a}$  is replaced by a  $\Gamma$ -equivalent tuple. In 1988 Győry and the author [4] showed that if  $K$  is a number field and  $\Gamma = U_S^n$ , i.e., the  $n$ -fold direct product of the group of  $S$ -units in  $K$ , then there are finitely many  $\Gamma$ -equivalence classes  $C_1, \dots, C_t$  such that for every tuple  $\mathbf{a} \in (K^*)^n \setminus (C_1 \cup \dots \cup C_t)$  the set of solutions of (1.2) is contained in the union of not more than  $2^{(n+1)!}$  proper linear subspaces of  $K^n$ . This was improved by the author [3, Thm. 8] to  $(n!)^{2n+2}$ . Both the proofs of Győry and the author and that of the author can be extended easily to arbitrary fields  $K$  of characteristic 0 and arbitrary subgroups  $\Gamma$  of  $(K^*)^n$  of finite rank.

For certain special groups  $\Gamma$ , Schlickewei and Viola [9, Corollary 2] improved the author's bound to  $\binom{2n+1}{n} - n^2 - n - 2$ . In fact, their result is valid for rank one groups  $\Gamma = \{(\alpha_1^z, \dots, \alpha_n^z) : z \in \mathbb{Z}\}$ , where  $\alpha_1, \dots, \alpha_n$  are non-zero elements of a field  $K$  of characteristic 0 such that neither  $\alpha_1, \dots, \alpha_n$ , nor any of the quotients  $\alpha_i/\alpha_j$  ( $0 \leq i < j \leq n$ ) is a root of unity.

In the present paper we deduce a further improvement for the general equation (1.2).

**Theorem.** *Let  $K$  be a field of characteristic 0, let  $n \geq 3$ , and let  $\Gamma$  be a subgroup of  $(K^*)^n$  of finite rank. Then there are finitely many  $\Gamma$ -equivalence classes  $C_1, \dots, C_t$  of tuples in  $(K^*)^n$ , such that for every  $\mathbf{a} = (a_1, \dots, a_n) \in (K^*)^n \setminus (C_1 \cup \dots \cup C_t)$ , the set of non-degenerate solutions of*

$$(1.2) \quad a_1x_1 + \dots + a_nx_n = 1 \quad \text{in } \mathbf{x} = (x_1, \dots, x_n) \in \Gamma$$

*is contained in the union of not more than  $2^n$  proper linear subspaces of  $K^n$ .*

We mention that the set of degenerate solutions of (1.2) is contained in the union of at most  $2^n - n - 2$  proper linear subspaces of  $K^n$ , each defined by a vanishing subsum  $\sum_{i \in I} a_i x_i = 0$  where  $I$  is a subset of  $\{1, \dots, n\}$  of cardinality  $\neq 0, 1, n$ . So for  $\mathbf{a} \notin C_1 \cup \dots \cup C_t$ , the set of (either degenerate or non-degenerate) solutions of (1.2) is contained in the union of at most  $2^{n+1} - n - 2$  proper linear subspaces of  $K^n$ .

Our main tool is a qualitative finiteness result due to Laurent [7] for the number of non-degenerate solutions in  $\Gamma$  of a system of polynomial equations (or rather for the number of non-degenerate points in  $X \cap \Gamma$  where  $X$  is an algebraic subvariety of the  $n$ -dimensional linear torus). Recently, Rémond [8] established for  $K = \overline{\mathbb{Q}}$  an explicit upper bound for the number of these non-degenerate solutions. Using the latter, it is possible to compute a (very large) explicit upper bound for the number  $t$  of exceptional equivalence classes, depending on  $n$  and the rank  $r$  of  $\Gamma$ . We have not worked this out.

In Section 2 we recall Laurent's result. In Section 3 we prove our Theorem. In Section 4 we give an example showing that our bound  $2^n$  cannot be improved to a quantity smaller than  $n$ .

## 2. POLYNOMIAL EQUATIONS

Let as before  $K$  be a field of characteristic 0, let  $n \geq 2$ , and let  $f_1, \dots, f_R \in K[X_1, \dots, X_n]$  be non-zero polynomials. Further, let  $\Gamma$  be a subgroup of  $(K^*)^n$  of finite rank. We consider the system of equations

$$(2.1) \quad f_i(x_1, \dots, x_n) = 0 \quad (i = 1, \dots, R) \quad \text{in } \mathbf{x} = (x_1, \dots, x_n) \in \Gamma.$$

Let  $\lambda$  be an auxiliary variable. A solution  $\mathbf{x} = (x_1, \dots, x_n)$  of system (2.1) is called *degenerate* if there are integers  $c_1, \dots, c_n$  with  $\gcd(c_1, \dots, c_n) = 1$  such that

$$(2.2) \quad f_i(\lambda^{c_1} x_1, \dots, \lambda^{c_n} x_n) = 0 \text{ identically in } \lambda \text{ for } i = 1, \dots, R$$

(meaning that by expanding the expressions, we get linear combinations of different powers of  $\lambda$ , all of whose coefficients are 0). Otherwise, the solution  $\mathbf{x}$  is called *non-degenerate*.

**Proposition 2.1.** *System (2.1) has only finitely many non-degenerate solutions.*

**Proof.** Without loss of generality we may assume that  $K$  is algebraically closed. Let  $X$  denote the set of points  $\mathbf{x} \in (K^*)^n$  with  $f_i(\mathbf{x}) = 0$  for  $i = 1, \dots, R$ . By a result of Laurent [7, Théorème 2], the set of solutions  $\mathbf{x} \in \Gamma$  of (2.1) is contained in the union of finitely many “families”  $\mathbf{x}H = \{\mathbf{x} \cdot \mathbf{y} : \mathbf{y} \in H\}$ , where  $\mathbf{x} \in \Gamma$  and where  $H$  is an irreducible algebraic subgroup of  $(K^*)^n$  such that  $\mathbf{x}H \subset X$ .<sup>1</sup>

Consider a family  $\mathbf{x}H$  with  $\mathbf{x} \in \Gamma$ ,  $\mathbf{x}H \subset X$ ,  $\dim H > 0$ . Pick a one-dimensional irreducible algebraic group  $H_0 \subset H$ . There are integers  $c_1, \dots, c_n$  with  $\gcd(c_1, \dots, c_n) = 1$  such that  $H_0 = \{(\lambda^{c_1}, \dots, \lambda^{c_n}) : \lambda \in K^*\}$ . Then  $\mathbf{x}H_0 = \{(x_0\lambda^{c_0}, \dots, x_n\lambda^{c_n}) : \lambda \in K^*\} \subset \mathbf{x}H \subset X$ , and the latter implies (2.2). Conversely, if  $\mathbf{x}$  satisfies (2.2) then  $\mathbf{x}H_0 \subset X$ . Therefore, the solutions of (2.1) contained in families  $\mathbf{x}H$  with  $\dim H > 0$  are precisely the degenerate solutions of (2.1). Each of the remaining families  $\mathbf{x}H$ , i.e., with  $\dim H = 0$  consists of a single solution  $\mathbf{x}$  since  $H = \{(1, \dots, 1)\}$ . It follows that system (2.1) has at most finitely many non-degenerate solutions.  $\square$

### 3. PROOF OF THE THEOREM

Let again  $K$  be a field of characteristic 0, let  $n \geq 3$ , and let  $\Gamma$  a subgroup of  $(K^*)^n$  of finite rank. Further, let  $\mathbf{a} = (a_1, \dots, a_n) \in (K^*)^n$ . We deal with

$$(1.2) \quad a_1x_1 + \cdots + a_nx_n = 1 \quad \text{in } \mathbf{x} = (x_1, \dots, x_n) \in \Gamma.$$

Assume that (1.2) has a non-degenerate solution. By replacing  $\mathbf{a}$  by a  $\Gamma$ -equivalent tuple we may assume that  $\mathbf{1} = (1, \dots, 1)$  is a non-degenerate solution of (1.2). This means that

$$(3.1) \quad \begin{cases} a_1 + \cdots + a_n = 1, \\ \sum_{i \in I} a_i \neq 0 \text{ for each non-empty subset } I \text{ of } \{1, \dots, n\}. \end{cases}$$

We will show that there is a finite set of tuples  $\mathbf{a}$  with (3.1) such that for each  $\mathbf{a} \in (K^*)^n$  outside this set, the set of non-degenerate solutions of (1.2) is contained in the union of not more than  $2^n$  proper linear subspaces of  $K^n$ . This clearly suffices to prove our Theorem.

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<sup>1</sup>For  $K = \overline{\mathbb{Q}}$ , Rémond [8, Thm. 1] showed that the set of solutions of (2.1) is contained in the union of at most  $(nd)^{n^3 m^{3m^2(r+1)}}$  families  $\mathbf{x}H$ , where  $r$  is the rank of  $\Gamma$ ,  $X$  has dimension  $m$ , and where each polynomial  $f_i$  has total degree  $\leq d$ . Probably his result can be extended to arbitrary fields  $K$  of characteristic 0 by means of a specialization argument.

By the result of Schlickewei, Schmidt and the author or that of Rémond mentioned in Section 1, there is a finite bound  $N$  independent of  $\mathbf{a}$  such that equation (1.2) has at most  $N$  non-degenerate solutions. (In fact, already Győry and the author [4] proved the existence of such a bound but their method did not allow to compute it explicitly).

For every tuple  $\mathbf{a}$  with (3.1), we make a sequence  $\mathbf{x}_1 = \mathbf{1}$ ,  $\mathbf{x}_2 = (x_{21}, \dots, x_{2n}), \dots, \mathbf{x}_N = (x_{N1}, \dots, x_{Nn})$  such that each term  $\mathbf{x}_i$  is a non-degenerate solution of (1.2) and such that each non-degenerate solution of (1.2) occurs at least once in the sequence. Then

$$(3.2) \quad \text{rank} \begin{pmatrix} 1 & \cdots & 1 & 1 \\ x_{21} & \cdots & x_{2n} & 1 \\ \vdots & & \vdots & \vdots \\ \vdots & & \vdots & \vdots \\ x_{N,1} & \cdots & x_{N,n} & 1 \end{pmatrix} \leq n$$

since the matrix has  $n + 1$  linearly dependent columns. Relation (3.2) means that the determinants of all  $(n + 1) \times (n + 1)$ -submatrices of the matrix on the left-hand side are 0. Thus, we may view (3.2) as a system of polynomial equations of the shape (2.1), to be solved in  $(\mathbf{x}_2, \dots, \mathbf{x}_N) \in \Gamma^{N-1}$ . It is important to notice that this system is independent of  $\mathbf{a}$ .

The tuples  $\mathbf{a}$  with (3.1) are now divided into three classes:

*Class I* consists of those tuples  $\mathbf{a}$  such that  $\text{rank} \{\mathbf{1}, \mathbf{x}_2, \dots, \mathbf{x}_N\} = n$  and such that  $(\mathbf{x}_2, \dots, \mathbf{x}_N)$  is a non-degenerate solution in  $\Gamma^{N-1}$  of system (3.2).

*Class II* consists of those tuples  $\mathbf{a}$  such that  $\text{rank} \{\mathbf{1}, \mathbf{x}_2, \dots, \mathbf{x}_N\} < n$ .

*Class III* consists of those tuples  $\mathbf{a}$  such that  $(\mathbf{x}_2, \dots, \mathbf{x}_N)$  is a degenerate solution in  $\Gamma^{N-1}$  of system (3.2).

First let  $\mathbf{a}$  be a tuple of Class I. By Proposition 2.1,  $(\mathbf{x}_2, \dots, \mathbf{x}_N)$  belongs to a finite set which is independent of  $\mathbf{a}$ . Now  $\mathbf{a} = (a_1, \dots, a_n)$  is a solution of the system of linear equations  $a_1 + \cdots + a_n = 1$ ,  $x_{i1}a_1 + \cdots + x_{in}a_n = 1$  ( $i = 2, \dots, N$ ). Since by assumption,  $\text{rank} \{\mathbf{1}, \mathbf{x}_2, \dots, \mathbf{x}_N\} = n$ , the tuple  $\mathbf{a}$  is uniquely determined by  $\mathbf{x}_2, \dots, \mathbf{x}_N$ . So Class I is finite.

For tuples  $\mathbf{a}$  from Class II, all non-degenerate solutions of (1.2) lie in a single proper subspace of  $K^n$ .

Now let  $\mathbf{a}$  be from Class III. In view of (2.2) this means that there are integers  $c_{ij}$  ( $i = 2, \dots, N, j = 1, \dots, n$ ), with  $\gcd(c_{ij} : i = 2, \dots, N, j = 1, \dots, n) = 1$ , such that

$$\text{rank} \begin{pmatrix} 1 & \cdots & 1 & 1 \\ \lambda^{c_{21}}x_{21} & \cdots & \lambda^{c_{2n}}x_{2n} & 1 \\ \vdots & & \vdots & \vdots \\ \vdots & & \vdots & \vdots \\ \lambda^{c_{N,1}}x_{N,1} & \cdots & \lambda^{c_{N,n}}x_{N,n} & 1 \end{pmatrix} \leqslant n$$

identically in  $\lambda$ , meaning that the determinants of the  $(n+1) \times (n+1)$ -submatrices of the left-hand side are identically zero in  $\lambda$ .

This implies that there are rational functions  $b_j(\lambda) \in K(\lambda)$  ( $j = 0, \dots, n$ ), not all equal to 0, such that

$$(3.3) \quad \sum_{j=1}^n b_j(\lambda) = b_0(\lambda), \quad \sum_{j=1}^n b_j(\lambda) \lambda^{c_{ij}} x_{ij} = b_0(\lambda) \quad (i = 2, \dots, N).$$

By clearing denominators, we may assume that  $b_0(\lambda), \dots, b_n(\lambda)$  are polynomials in  $K[\lambda]$  without a common zero.

We substitute  $\lambda = -1$ . Put  $b_j := b_j(-1)$  ( $j = 0, \dots, n$ ) and  $\varepsilon_{ij} := (-1)^{c_{ij}}$  ( $i = 2, \dots, N, j = 1, \dots, n$ ). Then  $(b_0, \dots, b_n) \neq (0, \dots, 0)$ , and the numbers  $\varepsilon_{ij}$  are not all equal to 1 since the integers  $c_{ij}$  are not all even. Further, by (3.3) we have

$$(3.4) \quad \begin{cases} b_1 + \cdots + b_n = b_0, \\ b_1 \varepsilon_{i1} x_{i1} + \cdots + b_n \varepsilon_{in} x_{in} = b_0 \quad \text{for } i = 2, \dots, N. \end{cases}$$

We claim that for each tuple  $(\varepsilon_1, \dots, \varepsilon_n) \in \{-1, 1\}^n$ , the tuple  $(b_1 \varepsilon_1, \dots, b_n \varepsilon_n, b_0)$  is not proportional to  $(a_1, \dots, a_n, 1)$ . Assuming this to be true, it follows from (3.4) that the set of non-degenerate solutions of (1.2) is contained in the union of at most  $2^n$  proper linear subspaces of  $K^n$ , each given by

$$b_0 \left( \sum_{j=1}^n a_j x_j \right) - \sum_{j=1}^n b_j \varepsilon_j x_j = 0$$

for certain  $\varepsilon_j \in \{-1, 1\}$  ( $j = 1, \dots, n$ ).

We prove our claim. First suppose that the tuple  $(b_1, \dots, b_n, b_0)$  is proportional to  $(a_1, \dots, a_n, 1)$ . There are  $i \in \{2, \dots, N\}$ ,  $j \in \{1, \dots, n\}$  such that  $\varepsilon_{ij} = -1$ . Now  $\mathbf{x}_i$  satisfies both  $\sum_{j=1}^n a_j x_{ij} = 1$  (since it is a solution of (1.2)) and  $\sum_{j=1}^n a_j \varepsilon_{ij} x_{ij} = 1$  (by (3.4)). But then by subtracting we obtain  $\sum_{j \in J} a_j x_{ij} = 0$ , where  $J$  is the set of indices  $j$  with  $\varepsilon_{ij} = -1$ . This is impossible since  $\mathbf{x}_i$  is a non-degenerate solution of (1.2).

Now suppose that  $(b_1 \varepsilon_1, \dots, b_n \varepsilon_n, b_0)$  is proportional to  $(a_1, \dots, a_n, 1)$  for certain  $\varepsilon_j \in \{-1, 1\}$ , not all equal to 1. Then by (3.1) and (3.4) we have  $\sum_{j=1}^n a_j = 1$ ,  $\sum_{j=1}^n a_j \varepsilon_j = 1$ . Again by subtracting, we obtain  $\sum_{j \in J} a_j = 0$  where  $J$  is the set of indices  $j$  with  $\varepsilon_j = -1$  and this is contradictory to (3.1). This proves our claim.

Summarizing, we have proved that Class I is finite, that for every  $\mathbf{a}$  in Class II, all solutions of (1.2) lie in a single proper linear subspace of  $K^n$ , and that for every  $\mathbf{a}$  in Class III, the solutions of (1.2) lie in the union of  $2^n$  proper linear subspaces of  $K^n$ . Our Theorem follows.  $\square$

#### 4. EQUATIONS WHOSE SOLUTIONS LIE IN MANY SUBSPACES

We give an example of a group  $\Gamma$  with the property that there are infinitely many  $\Gamma$ -equivalence classes of tuples  $\mathbf{a} = (a_1, \dots, a_n) \in (K^*)^n$  such that the set of non-degenerate solutions of (1.2) cannot be covered by fewer than  $n$  proper linear subspaces of  $K^n$ .

Let  $K$  be a field of characteristic 0, let  $n \geq 2$ , and let  $\Gamma_1$  be an infinite subgroup of  $K^*$  of finite rank. Take  $\Gamma := \Gamma_1^n = \{\mathbf{x} = (x_1, \dots, x_n) : x_i \in \Gamma_1 \text{ for } i = 1, \dots, n\}$ . Then  $\Gamma$  is a subgroup of  $(K^*)^n$  of finite rank.

Pick  $\mathbf{u} = (u_1, \dots, u_n) \in \Gamma$  with  $b := u_1 + \dots + u_n \neq 0$  and with  $\sum_{i \in I} u_i \neq 0$  for each non-empty subset  $I$  of  $\{1, \dots, n\}$ . Let  $S_n$  denote the group of permutations of  $\{1, \dots, n\}$ . For  $\sigma \in S_n$  write  $\mathbf{u}_\sigma := (u_{\sigma(1)}, \dots, u_{\sigma(n)})$ . Then  $\mathbf{u}_\sigma$  ( $\sigma \in S_n$ ) are non-degenerate solutions of

$$(4.1) \quad b^{-1}x_1 + \dots + b^{-1}x_n = 1 \quad \text{in } \mathbf{x} \in \Gamma.$$

For  $i = 1, \dots, n$ , the points  $\mathbf{u}_\sigma$  with  $\sigma(n) = i$  lie in the subspace given by

$$u_i(x_1 + \dots + x_{n-1}) - (b - u_i)x_n = 0.$$

Therefore, for fixed  $\mathbf{u}$ , the set  $\{\mathbf{u}_\sigma : \sigma \in S_n\}$  can be covered by  $n$  subspaces. We show that for “sufficiently general”  $\mathbf{u}$ , this set cannot be covered by fewer than  $n$  subspaces.

We need some auxiliary results.

**Lemma 4.1.** *Let  $n \geq 2$  and let  $S$  be a subset of  $S_n$  of cardinality  $> (n-1)!$ . Then there are  $\sigma_1, \dots, \sigma_n \in S$  such that the polynomial*

$$(4.2) \quad F_{\sigma_1, \dots, \sigma_n}(X_1, \dots, X_n) := \begin{vmatrix} X_{\sigma_1(1)} & \cdots & X_{\sigma_1(n)} \\ X_{\sigma_2(1)} & \cdots & X_{\sigma_2(n)} \\ \vdots & & \vdots \\ X_{\sigma_n(1)} & \cdots & X_{\sigma_n(n)} \end{vmatrix}$$

is not identically zero.

**Proof.** We proceed by induction on  $n$ . For  $n = 2$  the lemma is trivial. Assume that  $n \geq 3$ .

First assume there are  $i, j \in \{1, \dots, n\}$  such that the set  $S_{ij} = \{\sigma \in S : \sigma(i) = j\}$  has cardinality  $> (n-2)!$ . Then after a suitable permutation of the columns of the determinant of (4.2) and a permutation of the variables  $X_1, \dots, X_n$ , we obtain that  $S_{nn}$  has cardinality  $> (n-2)!$ . The elements of  $S_{nn}$  permute  $1, \dots, n-1$ . Therefore, by the induction hypothesis, there are  $\sigma_1, \dots, \sigma_{n-1} \in S_{nn}$  such that the polynomial

$$G(X_1, \dots, X_{n-1}) := \begin{vmatrix} X_{\sigma_1(1)} & \cdots & X_{\sigma_1(n-1)} \\ \vdots & & \vdots \\ X_{\sigma_{n-1}(1)} & \cdots & X_{\sigma_{n-1}(n-1)} \end{vmatrix}$$

is not identically zero. Since  $S_{nn}$  has cardinality  $\leq (n-1)!$ , there is a  $\sigma_n \in S$  with  $\sigma_n(n) = k \neq n$ . Therefore,

$$F_{\sigma_1, \dots, \sigma_n}(X_1, \dots, X_{n-1}, 0) = \pm X_k \cdot G(X_1, \dots, X_{n-1}) \neq 0.$$

So in particular,  $F_{\sigma_1, \dots, \sigma_n}$  is not identically zero.

Now suppose that for each pair  $i, j \in \{1, \dots, n\}$  the set  $S_{ij}$  has cardinality  $\leq (n-2)!$ . Together with our assumption that  $S$  has cardinality  $> (n-1)!$ , this implies that  $S_{ij} \neq \emptyset$  for  $i, j \in \{1, \dots, n\}$ . Thus, we may pick  $\sigma_1 \in S$  with  $\sigma_1(1) = 1$ ,  $\sigma_2 \in S$  with  $\sigma_2(2) = 1, \dots, \sigma_n \in S$  with  $\sigma_n(n) = 1$ . Then  $F_{\sigma_1, \dots, \sigma_n}(1, 0, \dots, 0) = 1$ , hence  $F_{\sigma_1, \dots, \sigma_n}$  is not identically zero.  $\square$

Let  $T$  denote the collection of tuples  $(\sigma_1, \dots, \sigma_n)$  in  $S_n$  for which  $F_{\sigma_1, \dots, \sigma_n}$  is not identically 0. Let  $B$  be the set of numbers of the shape  $u_1 + \dots + u_n$  where  $\mathbf{u} = (u_1, \dots, u_n)$  runs through all tuples in  $\Gamma = \Gamma_1^n$  with

$$(4.3) \quad \begin{cases} \sum_{i \in I} u_i \neq 0 & \text{for each } I \subseteq \{1, \dots, n\} \text{ with } I \neq \emptyset; \\ F_{\sigma_1, \dots, \sigma_n}(u_1, \dots, u_n) \neq 0 & \text{for each } (\sigma_1, \dots, \sigma_n) \in T. \end{cases}$$

In particular (taking  $I = \{1, \dots, n\}$ ), each  $b \in B$  is non-zero.

Two numbers  $b_1, b_2 \in K^*$  are called  $\Gamma_1$ -equivalent if  $b_1/b_2 \in \Gamma_1$ .

**Lemma 4.2.** *The set  $B$  is not contained in the union of finitely many  $\Gamma_1$ -equivalence classes.*

**Proof.** First suppose that  $B \neq \emptyset$ . Assume that  $B$  is contained in the union of finitely many  $\Gamma_1$ -equivalence classes. Let  $b_1, \dots, b_t$  be representatives for these classes. Then for every  $\mathbf{u} = (u_1, \dots, u_n) \in \Gamma$  with (4.3) there are  $b_i \in \{b_1, \dots, b_t\}$  and  $u \in \Gamma_1$  such that

$$u_1 + \dots + u_n = b_i u.$$

Hence for given  $b_i$ ,  $(u_1/u, \dots, u_n/u)$  is a non-degenerate solution of

$$x_1 + \dots + x_n = b_i \quad \text{in } \mathbf{x} = (x_1, \dots, x_n) \in \Gamma.$$

Each such equation has only finitely many non-degenerate solutions. Therefore, for each  $b_i$  there are only finitely many possibilities for  $(u_1/u, \dots, u_n/u)$ , hence only finitely many possibilities for  $u_1/u_2$ . So if  $(u_1, \dots, u_n)$  runs through all tuples in  $\Gamma$  with (4.3), then  $u_1/u_2$  runs through a finite set,  $U$ , say.

Now let  $F$  be the product of the polynomials  $F_{\sigma_1, \dots, \sigma_n}$  ( $(\sigma_1, \dots, \sigma_n) \in T$ ),  $\sum_{i \in I} X_i$  ( $I \subseteq \{1, \dots, n\}$ ,  $I \neq \emptyset$ ) and  $X_1 - uX_2$  ( $u \in U$ ). Then  $F(u_1, \dots, u_n) = 0$  for every  $u_1, \dots, u_n \in \Gamma_1$ . But since  $\Gamma_1$  is infinite, this implies that  $F$  is identically zero. Thus, if we assume that  $B \neq \emptyset$  and that Lemma 4.2 is false we obtain a contradiction. The assumption  $B = \emptyset$  leads to a contradiction in a similar manner, taking for  $F$  the product of the polynomials  $F_{\sigma_1, \dots, \sigma_n}$  ( $(\sigma_1, \dots, \sigma_n) \in T$ ),  $\sum_{i \in I} X_i$  ( $I \subseteq \{1, \dots, n\}$ ,  $I \neq \emptyset$ ).  $\square$

Lemma 4.2 implies that the collection of tuples  $(b^{-1}, \dots, b^{-1})$  ( $n$  times) with  $b \in B$  is not contained in the union of finitely many  $\Gamma$ -equivalence classes. We show that for every  $b \in B$ , the set of non-degenerate solutions of (4.1) cannot be covered by fewer than  $n$  proper linear subspaces of  $K^n$ .

Choose  $b \in B$ , and choose  $\mathbf{u} = (u_1, \dots, u_n) \in \Gamma$  with  $u_1 + \dots + u_n = b$  and with (4.3). Then each vector  $\mathbf{u}_\sigma$  ( $\sigma \in S_n$ ) is a non-degenerate solution of (4.1).

We claim that a proper linear subspace of  $K^n$  cannot contain more than  $(n-1)!$  vectors  $\mathbf{u}_\sigma$  ( $\sigma \in S_n$ ). For suppose some subspace  $L$  of  $K^n$  contains more than  $(n-1)!$  vectors  $\mathbf{u}_\sigma$ . Then by Lemma 4.1, there are  $\sigma_1, \dots, \sigma_n \in S_n$  such that  $\mathbf{u}_{\sigma_i} \in L$  for  $i = 1, \dots, n$  and such that  $F_{\sigma_1, \dots, \sigma_n}$  is not identically 0. But since  $\mathbf{u}$  satisfies (4.3), we have  $F_{\sigma_1, \dots, \sigma_n}(\mathbf{u}) \neq 0$ . Therefore, the vectors  $\mathbf{u}_{\sigma_1}, \dots, \mathbf{u}_{\sigma_n}$  are linearly independent. Hence  $L = K^n$ .

Our claim shows that at least  $n$  proper linear subspaces of  $K^n$  are needed to cover the set  $\mathbf{u}_\sigma$  ( $\sigma \in S_n$ ). Therefore, the set of non-degenerate solutions of (4.1) cannot lie in the union of fewer than  $n$  proper subspaces.

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